應用力學下 Final 命題老師:廖國基教授 注意: 所有題目均需詳列計過程,否則不予計分。 1. 2. 除計算機外,禁止使用如書籍、筆記、講義等任何形式之輔助工具。

請於試卷謄寫下列之 Honor Code。 3.

"本人於此次考試中沒有接受任何形式之外部協助作答"(簽名)

If P = 130 N, determine the angular acceleration of the 22.5 kg roller. Assume the roller to be a 1. uniform cylinder and that no slipping occurs.



$$I_{G} = \frac{1}{2}mr^{2} = \frac{1}{2}(22.5)(0.45)^{2} = 2.278 \text{ kg} \cdot m^{2}$$

$$\Rightarrow \Sigma F_{x} = m(Q_{G})_{x}; \quad 120 \cos 2n^{2} - F_{y} = 32 F_{y} = 0$$

.

$$\rightarrow 2F_x = m(0.6)_x$$
; 130 cos30 - Ff = 22.5 Q.6 -(1)
+ $f \Sigma F_y = m(0.6)_y$; N - 22.5 (9.81) - 130 stn 30° = 0
N = 285,73 N

Since the roller rolls without slipping $a_{g} = \alpha r = 0.45 \alpha - (3)$

Solving (1) - (3) $\Rightarrow \alpha = 7.413 \text{ rad}_{5^2}$ 2. Rod *AB* rotates counterclockwise with a constant angular velocity $\omega = 3$ rad/s. Determine the velocity and acceleration of point *C* located on the double collar when $\theta = 45^{\circ}$. The collar consists of two pin-connected slider blocks which are constrained to move along the circular path and the rod *AB*.



SOLUTION

 $\mathbf{r}_{C/A} = \{0.400\mathbf{i} + 0.400\mathbf{j}\}$ $\mathbf{v}_C = -v_C \mathbf{i}$ $\mathbf{v}_C = \mathbf{v}_A + \mathbf{\Omega} \times \mathbf{r}_{C/A} + (\mathbf{v}_{C/A})_{xyz}$ $-v_{C}\mathbf{i} = 0 + (3\mathbf{k}) \times (0.400\mathbf{i} + 0.400\mathbf{j}) + (v_{C/A}\cos 45^{\circ}\mathbf{i} + v_{C/A}\sin 45^{\circ}\mathbf{j})$ $-v_{C}\mathbf{i} = 0 - 1.20\mathbf{i} + 1.20\mathbf{j} + 0.707v_{C/A}\mathbf{i} + 0.707v_{C/A}\mathbf{j}$ $-v_{C} = -1.20 + 0.707 v_{C/A}$ $0 = 1.20 + 0.707 v_{C/A}$ $v_{C} = 2.40 \text{ m/s}$ Ans. $v_{C/A} = -1.697 \text{ m/s}$ $\mathbf{a}_{C} = \mathbf{a}_{A} + \dot{\Omega} \times \mathbf{r}_{C/A} + \Omega \times (\Omega \times \mathbf{r}_{C/A}) + 2\Omega \times (\mathbf{v}_{C/A})_{xyz} + (\mathbf{a}_{C/A})_{xyz}$ $-(a_C)_{\mathbf{i}}\mathbf{i} - \frac{(2.40)^2}{0.4}\mathbf{j} = 0 + 0 + 3\mathbf{k} \times [3\mathbf{k} \times (0.4\mathbf{i} + 0.4\mathbf{j})] + 2(3\mathbf{k}) \times [0.707(-1.697)\mathbf{i}]$ + 0.707(-1.697)**j**] + $0.707a_{C/A}$ **i** + $0.707a_{C/A}$ **j** $-(a_C)_t \mathbf{i} - 14.40 \mathbf{j} = 0 + 0 - 3.60 \mathbf{i} - 3.60 \mathbf{j} + 7.20 \mathbf{i} - 7.20 \mathbf{j} + 0.707 a_{C/A} \mathbf{i} + 0.707 a_{C/A} \mathbf{j}$ $-(a_C)_t = -3.60 + 7.20 + 0.707a_{C/A}$ $-14.40 = -3.60 - 7.20 + 0.707a_{C/A}$ $a_{C/A} = -5.09 \text{ m/s}^2$ $(a_C)_t = 0$ Thus. $a_C = (a_C)_n = \frac{(2.40)^2}{0.4} = 14.4 \text{ m/s}^2$ $a_C = \{-14.4\mathbf{j}\} \text{ m/s}^2$ Ans.

3. The 230-kg beam is supported at *A* and *B* when it is subjected to a force of 4.5-kN as shown. If the pin support at *A* suddenly fails, determine the beam's initial angular acceleration and the force of the roller support on the beam. For the calculation, assume that the beam is a slender rod so that its thickness can be neglected.



$$\begin{split} \leftarrow \sum F_{x} = m(\Delta_{6})_{x}; & 4500(\frac{4}{5}) = 230(\Delta_{6})_{x} \\ + \sqrt{2} F_{y} = m(\Delta_{6})_{y}; & 4500(\frac{3}{5}) + 230(4.81) - B_{y} = 230(\Delta_{6})_{y} \\ (j + \sum (M_{k})_{B}; & 230(9.81)(0.9) + 4500(\frac{3}{5})(2.4) = 230(\Delta_{6})_{y}(0.9) + \left[\frac{1}{12}(230)(3)\right] \\ & \Delta_{B} = \Delta_{6} + \Delta_{B/6} \\ & -\Delta_{B}\hat{i} = -(\Delta_{6})_{x}\hat{i} - (\Delta_{6})_{y}\hat{j} + \alpha(3)\hat{j} \\ & (\Delta_{6})_{y} = \alpha(3) \\ & \alpha = 23.71 r^{ad}/s^{\perp} + A_{ns}, \\ & B_{y} = 48.33 N + A_{ns}, \end{split}$$



4. The 10-kg uniform slender rod is suspended at rest when the force of F = 150 N is applied to its end. Determine the angular velocity of the rod when it has rotated 90° clockwise from the position shown. The force is always perpendicular to the rod.



Ans.

Kinetic Energy. Since the rod starts from rest, $T_1 = 0$. The mass moment of inertia of the rod about O is $I_0 = \frac{1}{12} (10)(3^2) + 10(1.5^2) = 30.0 \text{ kg} \cdot \text{m}^2$. Thus,

$$T_2 = \frac{1}{2} I_0 \omega^2 = \frac{1}{2} (30.0) \, \omega^2 = 15.0 \, \omega^2$$

Work. Referring to the FBD of the rod, Fig. *a*, when the rod undergoes an angular displacement θ , force **F** does positive work whereas **W** does negative work. When $\theta = 90^\circ$, $S_W = 1.5$ m and $S_F = \theta r = \left(\frac{\pi}{2}\right)(3) = \frac{3\pi}{2}$ m. Thus

$$U_F = 150\left(\frac{3\pi}{2}\right) = 225\pi \text{ J}$$

 $U_W = -10(9.81)(1.5) = -147.15 \text{ J}$

Principle of Work and Energy.

$$T_1 + \Sigma U_{1-2} = T_2$$

0 + 225\pi + (-147.15) = 15.0 \omega^2
\omega = 6.1085 \text{ rad/s} = 6.11 \text{ rad/s}



5. In the eccentric shown, a disk of 50-mm-radius revolves about shaft *O* that is located 12 mm from the center *A* of the disk. The distance between the center *A* of the disk and the pin at *B* is 200 mm. Knowing that the angular velocity of the disk is 900 rpm clockwise, determine the velocity of the block when $\theta = 30^{\circ}$.



6. The 150-kg uniform crate rests on the 10-kg cart. Determine the maximum force *P* that can be applied to the handle without causing the crate to slip or tip on the cart. The coefficient of static friction between the crate and cart is $\mu_s = 0.2$.



Equation of Motion. Assuming that the crate slips before it tips, then $F_f = \mu_s N = 0.2$ N. Referring to the FBD and kinetic diagram of the crate, Fig. *a*

$+\uparrow\Sigma F_y = ma_y;$	N - 150 (9.81) = 150 (0)	N = 1471.5 N
$\stackrel{+}{\leftarrow} \Sigma F_x = m(a_G)_x;$	0.2(1471.5) = 150 a	$a = 1.962 \text{ m/s}^2$
$\zeta + \Sigma M_A = (M_k)_A;$	150(9.81)(x) = 150(1.96)	62)(0.5)
	$x = 0.1 \mathrm{m}$	

Since x = 0.1 m < 0.25 m, the crate indeed slips before it tips. Using the result of *a* and refer to the FBD of the crate and cart, Fig. *b*,

 $\stackrel{+}{\leftarrow} \Sigma F_x = m(a_G)_x;$ P = (150 + 10)(1.962) = 313.92 N = 314 N Ans.

